

Fast Rotating Relativistic Stars: Spectra and Stability without Approximation

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Motivation and Aim

- Knowledge of NS oscillation frequencies and damping times are essential for asteroseismology.
- Previous studies always relied on simplifications due to complexity of the problem such as
 - Newtonian gravitation,
 - slow-rotation approximation.
 - Cowling approximation,
- Provide universal relations to help solve the *inverse problem*, i.e. turn NS frequencies and/or damping times into NS bulk parameters (mass, radius, ...).

Equations to solve

- Einstein equations

$$G_{\mu\nu} = 8\pi T_{\mu\nu}, \quad \nabla_\mu T^{\mu\nu} = 0$$

- Neutron star modelled as perfect fluid

$$T^{\mu\nu} = (\epsilon + p)u^\mu u^\nu + pg^{\mu\nu}$$

- Metric describing a rotating star can be written as

$$ds^2 = -e^{2\nu} dt^2 + e^{2\psi} r^2 \sin^2 \theta (d\phi - \omega dt)^2 + e^{2\mu} (dr^2 + r^2 d\theta^2)$$

- Use the rns-code to solve these equations and construct equilibrium models.

Linear Perturbation Theory

- Introduce small, time-dependent perturbations away from equilibrium:

$$q(t, r, \theta, \phi) = \bar{q}(r, \theta) + \delta q(t, r, \theta, \phi)$$

- Expand the Einstein equations and throw away all terms that are non-linear in the perturbations.
→ Resulting equations are somewhat lengthy...
- We pick the *Hilbert gauge* which is the analogue to the Lorenz gauge in E/M:

$$\nabla_\mu h^\mu_\nu = 0$$

($h_{\mu\nu}$ are the metric perturbations.)

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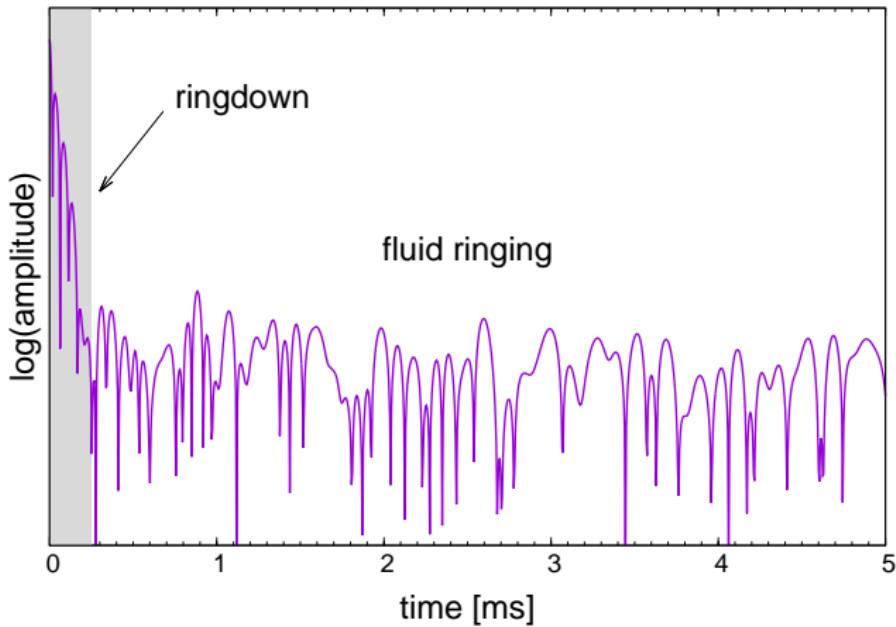
($h_{\mu\nu}$ are the metric perturbations.)

Exemplary: The wave equation for $h_{tt} \sim L$

$$\begin{aligned}
& \frac{(e^*)^2 \left(\frac{\partial^2}{\partial r^2} LL \right)}{(e^*)^2} = 8 (e^*)^2 (\sigma^*)^4 \pi Q \beta + \left[8 \pi u_- r^2 (\rho + p) (-\Omega + \omega) (e^*)^2 (e^y)^2 (e^*)^2 \right. \\
& \quad \left. - \frac{(2 \mu_r \omega_r)^2 - 8 \nu_r \omega_r^2 - 2 \nu_{r,r}^2 - 6 r \omega_r - 3 \nu_y \omega_y + \nu_y \omega_y - \omega_0 \cot(\theta) - \omega_{0,0}) (e^*)^2}{r^2} \right] AA + 2 (e^*)^2 \nu_r \left(\frac{\partial}{\partial r} AA \right) + \frac{(e^*)^2 \left(\frac{\partial}{\partial \theta} AA \right) u_y}{r^2} \\
& + \left(3 \omega_r \nu_y + \omega_r v_y + \omega_r \cot(\theta) - 2 \mu_r \omega_y + 2 \nu_r \omega_y + \omega_{r,y} \right) (e^*)^2 BB + (e^*)^2 \nu_y \left(\frac{\partial}{\partial \theta} BB \right) + \left[\left(8 \pi u_- r^2 (\rho + p) (e^*)^2 - 8 \pi p - \frac{m^2}{\sin(\theta)^2 (e^*)^2 r^2} \right. \right. \\
& \quad \left. + \frac{a^2 m^2}{(e^*)^2} \right) (e^*)^2 - \frac{1}{r^2} (2 \mu_r \nu_r r^2 + 2 \mu_r v_r r^2 + 2 \nu_r^2 r^2 - \nu_{r,r}^2 r^2 + 2 \nu_{r,r} r^2 + \nu_{r,r}^2 r^2 + 6 \nu_r r - 4 \mu_y \nu_y + 2 \nu_y^2 + 2 \nu_y v_y \\
& \quad + 4 \nu_y \cot(\theta) + 2 v_y^2 + 2 \nu_y \cot(\theta) + 2 \nu_{y,y} + 2 \nu_{y,r} + 2 \nu_{y,y} + 2) - \frac{1}{2} \frac{\sin(\theta)^2 (r \omega_r - \omega_0) (r \omega_r + \omega_0) (e^*)^2}{(e^*)^2} \right] LL \\
& - \frac{(2 \mu_r r - \nu_r r - \nu_r r - 2) \left(\frac{\partial}{\partial r} LL \right)}{r} - \frac{(2 \mu_y + \nu_y - \nu_y - \cot(\theta)) \left(\frac{\partial}{\partial \theta} LL \right)}{r^2} + \left[\right. \\
& \quad \left. 2 \mu_r \nu_y r + 2 \nu_r \nu_y r + 2 \mu_r \cot(\theta) r + 4 \mu_y \nu_y r - 2 \nu_r \nu_y r - 2 \nu_y \nu_y r - 2 \nu_y \cot(\theta) r - \nu_{r,y} r - 3 \nu_{r,y} r + 2 \nu_y + 2 \nu_y + 2 \cot(\theta) \right. \\
& \quad \left. - \frac{\sin(\theta)^2 (e^*)^2 \omega_r u_y}{r^2} \right] MM + \frac{2 \nu_y \left(\frac{\partial}{\partial r} MM \right)}{r^2} - \frac{2 (\nu_r r - \nu_r r + 1) \left(\frac{\partial}{\partial \theta} MM \right)}{r^2} + \frac{\frac{\partial^2}{\partial r^2} LL}{\partial r^2} + \frac{\frac{\partial^2}{\partial \theta^2} LL}{\partial \theta^2} + 4 \nu_r (e^*)^2 \left(\frac{\partial}{\partial r} KK \right) \\
& + \frac{2 \nu_y (e^*)^2 \left(\frac{\partial}{\partial \theta} QQ \right)}{r^2} + \left(\frac{21 \nu_y m (\nu_r r - \nu_r r + 1) (e^*)^2}{\sin(\theta)^2 r^2} \right. \\
& \quad \left. - \frac{1 m \left(-4 KK \nu_r \omega r^2 + 2 \omega_r KK r^2 - 2 \omega_r HH r^2 + 2 \omega_r WW r^2 - 2 QQ \nu_y \omega + QQ \omega_y \right)}{r^2} - \frac{21 m \left(\frac{\partial}{\partial r} LL \right)}{(e^*)^2} \right) (e^*)^2
\end{aligned}$$

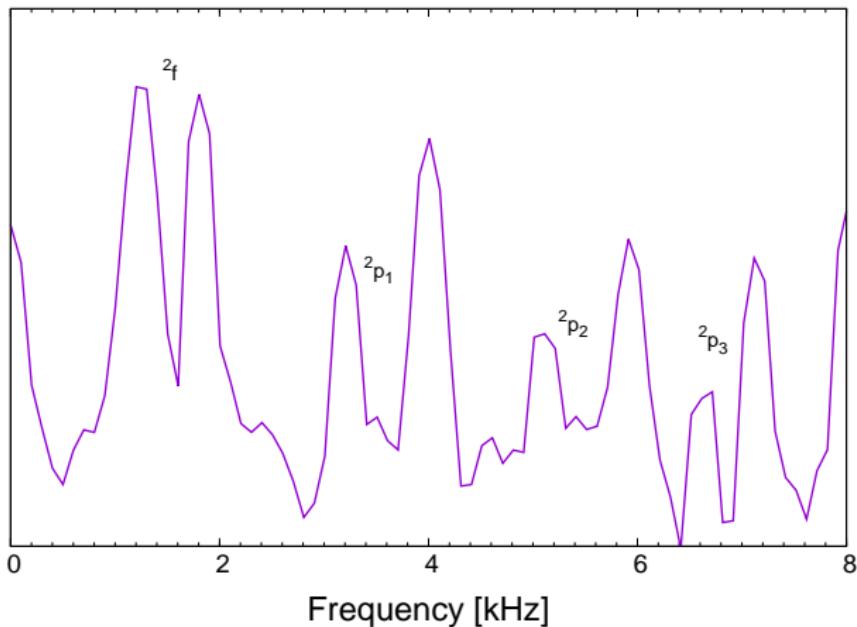
Have 10 such equations for the spacetime
and 4 equations for the fluid.

Echo from a rotating neutron star



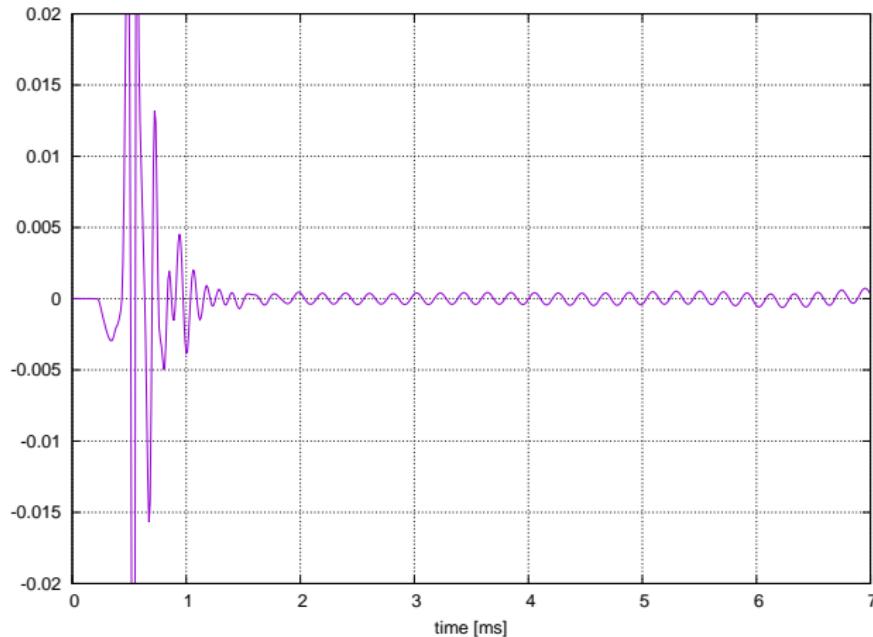
Observe ringdown ($t \in [0.0 \text{ ms}, 0.25 \text{ ms}]$),
followed by fluid ringing ($t > 0.25 \text{ ms}$).

Spectral density of fluid ringing



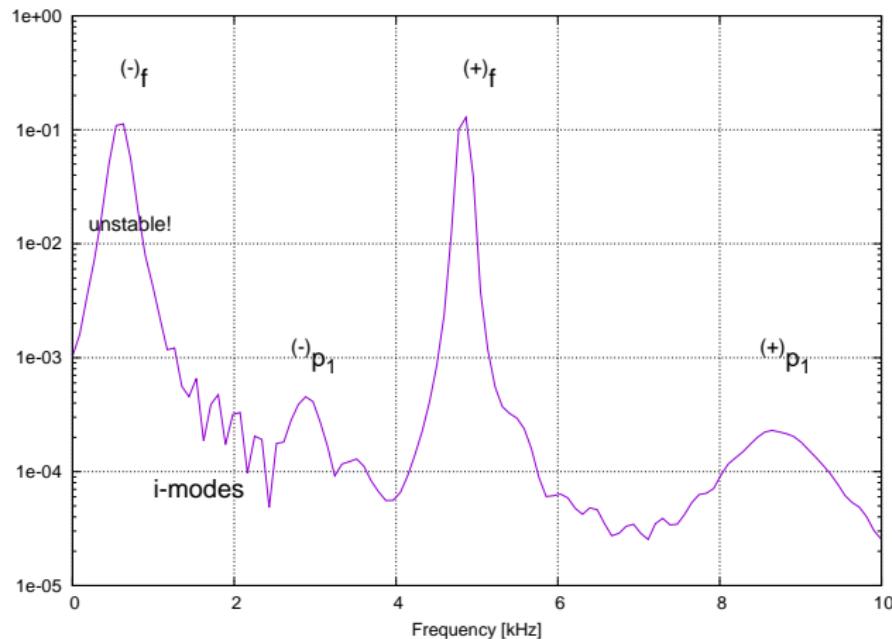
"Zeeman" splitting of the fundamental mode and its overtones clearly visible.

Echo from a fast rotating star



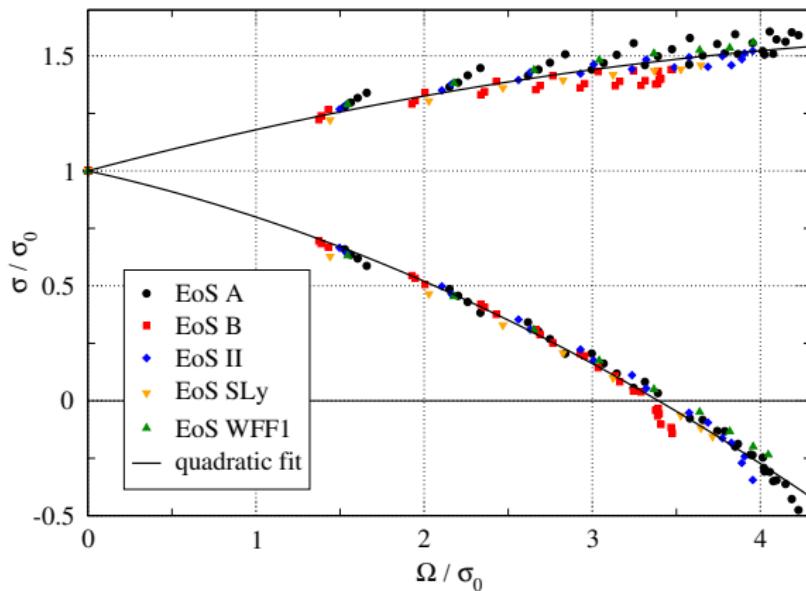
EoS SLy, $M = 2.0 M_{\odot}$, $\Omega = 1.3 \text{ kHz}$, $\Omega/\Omega_K = 0.98$.

Spectral density of fast rotating star



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How the f -mode frequency changes with NS rotation



- Curves show universal behaviour.
- f -mode becomes unstable when $\Omega \gtrsim 3.4\sigma_0$.

A different model for the f -mode frequency¹

- Define parameter “*effective compactness*”

$$\eta := \sqrt{\left(\frac{M}{M_\odot}\right)^3 \left(\frac{I}{10^{45} \text{ g cm}^2}\right)^{-1}}.$$

- Turns out to be useful parameter for fitting formula.
- Typical values for uniformly rotating NS are $\eta \in [1.0, 2.3]$.

¹inspired by Doneva, Kokkotas (2015) PRD 92, 124004

- Modeling f -mode frequency, σ , via²

$$M\sigma = \left(a_1 + a_2 \hat{\Omega} + a_3 \hat{\Omega}^2 \right) + \left(b_1 + \cancel{b_2 \hat{\Omega}} + b_3 \hat{\Omega}^2 \right) \eta,$$

with $\hat{\Omega} = M\Omega$.

- 3 parameters: mass, rotation rate, moment of inertia.
- Fitting values from 126 simulations yields

$$\begin{aligned} a_1 &= -2.1 \quad (2.5\%), & b_1 &= 3.4 \quad (1.0\%), \\ a_2 &= -0.20 \quad (0.9\%), & b_2 &= 0.0, \\ a_3 &= -8.5 \cdot 10^{-3} \quad (5.7\%), & b_3 &= -2.2 \cdot 10^{-3} \quad (10\%). \end{aligned}$$

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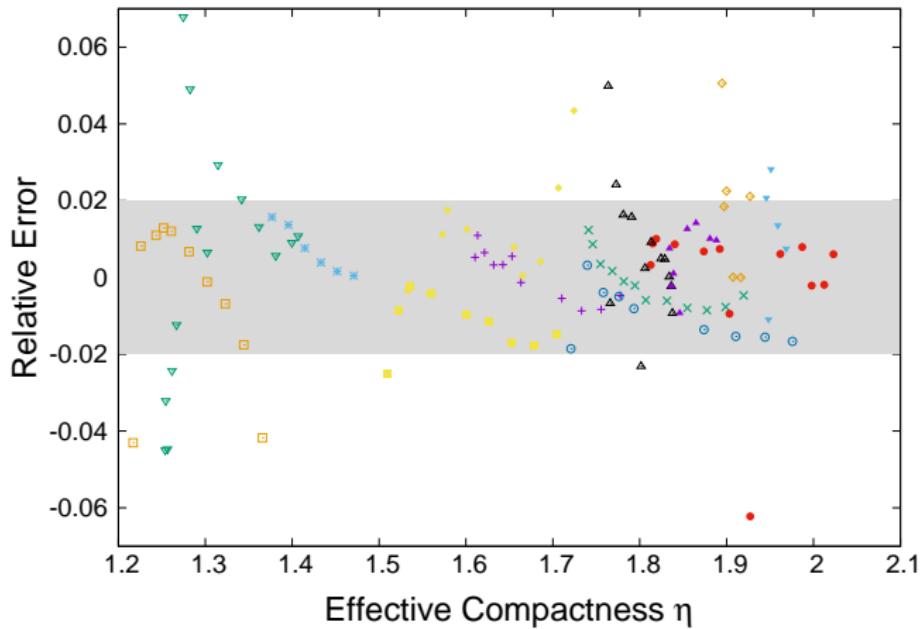
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Relative Error of model for f -mode frequency



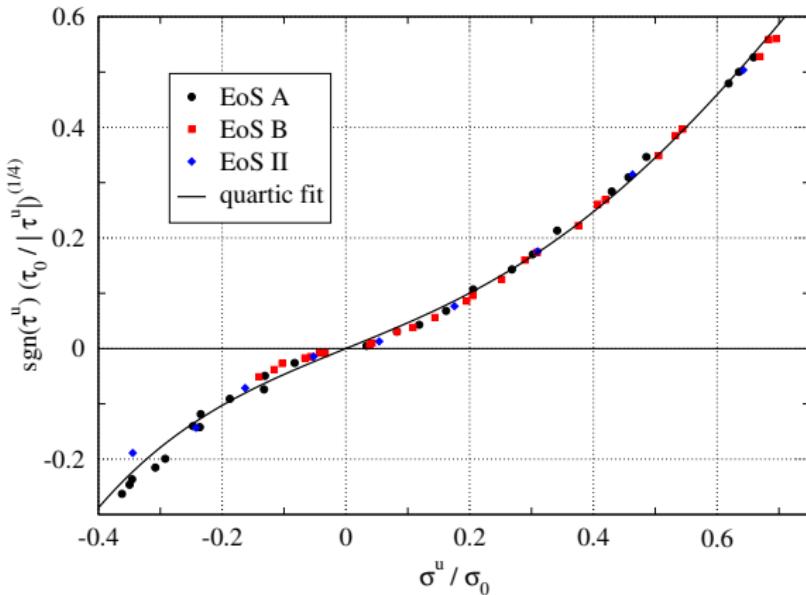
The model deviates less than 2% for the majority of simulations.

Damping time of the *f*-mode

- Difficult to determine from the simulation
- Approximate using Quadrupole formula:

$$\tau = -\frac{2E_{kin}}{\langle dE/dt \rangle_{GW}}$$

Damping time of the f -mode



Conclusions and Outlook

- First fitting formulae for f -mode frequency in full GR.
- Extract w -mode frequencies from ringdown and damping times of various modes.
- Find different universal relations.
- Do asteroseismology.